

COLLEGE OF SCIENCE AND TECHNOLOGY SCHOOL OF ENGINEERING DEPARTMENT OF CIVIL, ENVIRONMENTAL AND GEOMATIC ENGINEERING

END OF SEMESTER II EXAMINATION -ACADEMIC YEAR 2024-2025

YEAR: 2 & 3

SEMESTER: II

PROGRAMME: (SGE)

MODULE: SGE2264 and SGE3262 PHOTOGRAMMETRY II

DATE: 05 /06/2025

TIME: 2hours

MAXIMUM MARKS = 50

INSTRUCTIONS

1. This paper contains FOUR (4) questions.

2. Answer THREE (3) Questions only:

Question ONE (1) from Section "A" is Compulsory and Answer any TWO (2) from
Section "B"

- 3. Any written materials and Programmable calculators are NOT allowed.
- 4. Do not forget to write your Registration Number.
- 5. Write all your answers in the booklet provided
- 6. Do not write any answers on this question paper.
- 7. Start each question on a NEW page

SECTION: A

Qu	estion: 1	[20]
a)	Rwanda Environmental Management Authority (REMA) would like to conduct a acquire LIDAR Topographic data and visible/near infrared images for the community resilience, those data will be used as input to develop different prosurveyor and geomatic engineer of this project: i. Explain why establishing photo control points is a crucial step for project ii. Give examples of objects that can be selected as horizontal and control points for photogrammetric operations iii. Describe the raw data that can be derived from LIDAR surveying iv. Name the 3 products that could be generated from these data.	volcanoes oducts. As this [1] vertical [2]
	A typical aerial survey consists of photos at a scale of 1:4800, the desire resolution for the orthophoto is approximately 30cm. For a 22.86cm aerial phowhat is the scanning resolution in dot per inch?	tograph,
c)	Discuss the differences between laser scanning and photography and explain the of collecting both at the same time	benefits [4]
	Camera calibration is very important step in close-range photogrammetry, dis- methods of camera calibration, why do you think this step is very impo- photogrammetry? What do you understand by digital photogrammetric workstations (DPW)?	
Qı	SECTION: B restion: 2	
	a) Aerial photography is to be taken from a flying height of 6000 ft (1828.8m) above a ground with a camera having a 6-in (152.4mm) focal length and a 9in (23cm) form lap will be 60 percent, and side lap will be 30 percent. What is the ground area is covered by a single photograph and by the stereoscopic neat model? [3]	Company of the company of the
	b) Write short notes on the following terms used in Photogrammetry II i) Tie points ii) Bundle Adjustment iii) Image Matching iv) Digital orthophoto image v) Bridging	
	 c) Briefly explain the source of errors in orthophoto generation d) Discuss the differences between laser scanning and photography and explain the benefits of collecting both at the same time. Page 1 of 2	[4] e [3]

Question: 3				[15]
facacin. 2				

a	Discuss the advantages of	aerial	triangulation over	ground surveying n	nethods.	[2]
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b) A lasermounted on an airplane emits a pulse that reflects off a target and returns the sensor in 0.0062003 millisecond. Assume that the pulse is aimed directly down to the datum surface, that the speed of light in air is 299,703,000m/s, and that the laser is at exactly 1.2 km above the datum.

What is the object's height above datum? [4]

- c) Differentiate airborne laser scanning to terrestrial laser scanning and list the types of terrestrial laser scanners existing on the current market?
- d) Image matching techniques are broadly categorized into two approaches. Explain these two categories in detail, and for each, describe the main techniques used [5]

Question: 4 [15

- a) Suppose that the project area is 18 km in the north-south direction and 26 km in the east west direction and is to be photographed at a scale of 1:12000, End lap and side lap are 6 and 30 percent, respectively, the average velocity of the aircraft is 300 km/h and the camer format is 23 cm square. Align the first and last flight lines with 0.3S (side lap dimension coverage outside the north and south project boundary lines
 - i. Prepare a flight map on a 1:24000 base map [3
 - ii. Compute the total number of photographs needed to cover the area [5
 - ii. Compute the total time of photography [1
- b) Describe the three categories of aero-triangulation. Which category is the most accurate? Justify your answer
- c) Discuss some of the uses of terrestrial or close-range photogrammetry [3